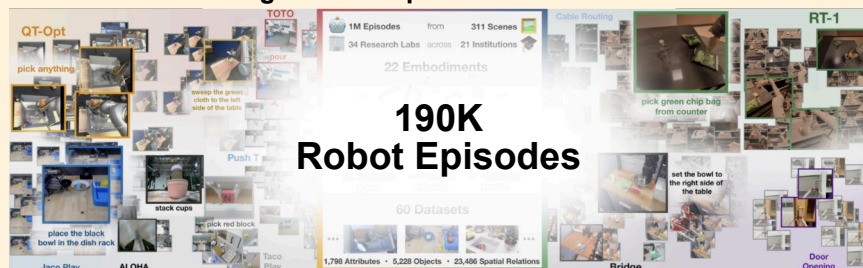


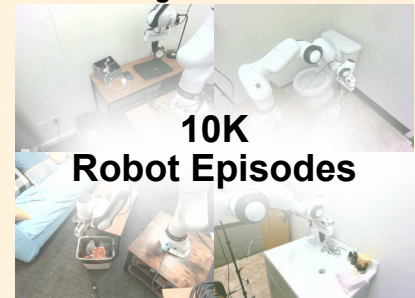
Data

Action Reasoning Data

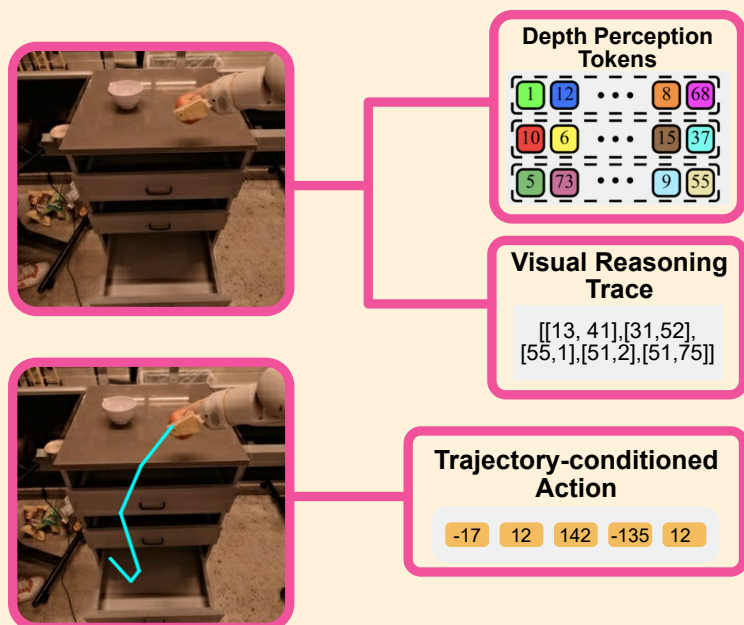
Pre-training Filtered Open-X Embodiment Dataset



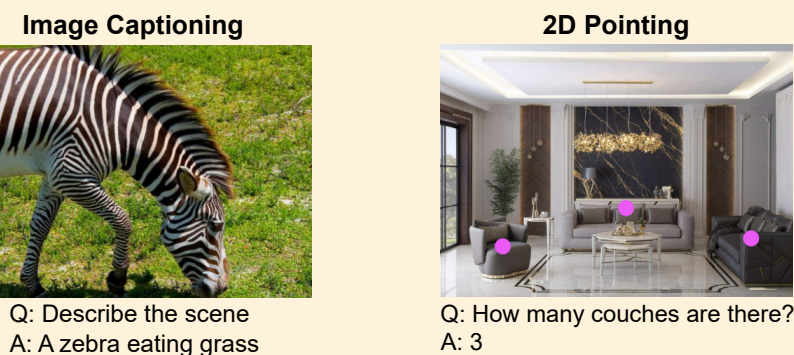
Mid-training MolmoAct Dataset



Auxiliary Robot Data



Multimodal Web Data



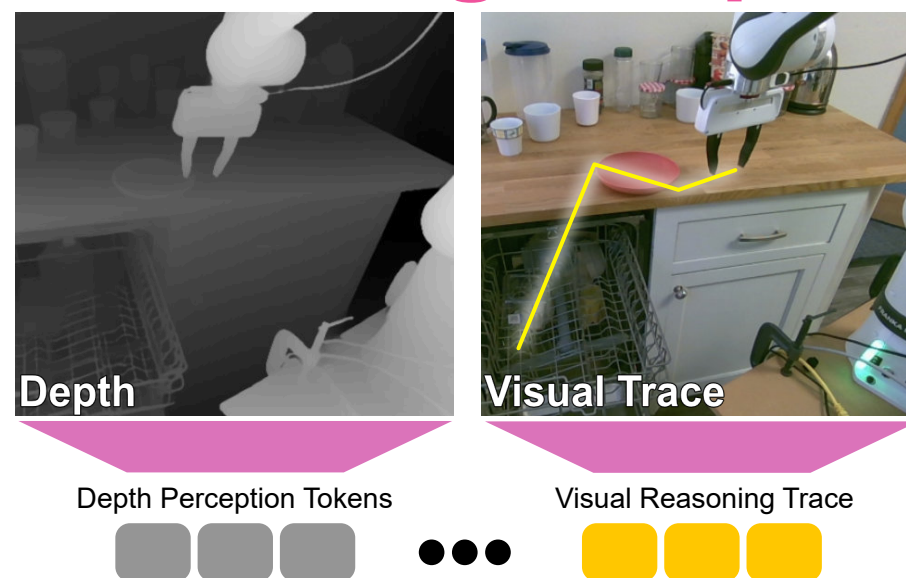
Input



"Put the plate in the dishwasher"

MolmoAct

Reasoning in Space

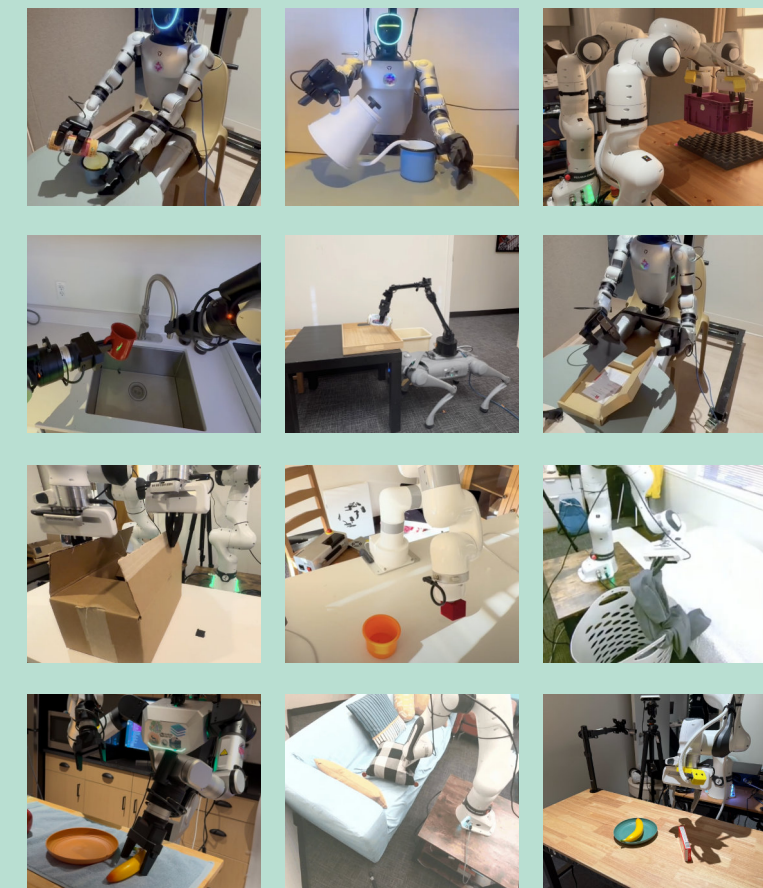


Output



Deployment

Deployment into real-world



Steerability

